

# Disentangling Overlapping Astronomical Sources using Spatial, Spectral, and Temporal Information

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SAMSI and Duke University

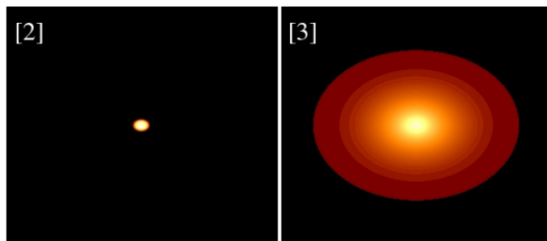
Collaborators: Vinay Kashyap (CfA), David van Dyk (Imperial College Statistics),  
Luis Campos (Harvard)

International CHASC Astrostatistics Center

SAMSI ASTRO Workshop

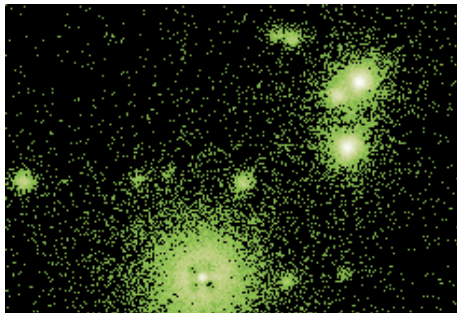
August 21, 2016

- Chandra and XMM-Newton X-ray telescope data:
  - spatial coordinates of photon detections
  - photon energy (PI channel)
- Telescope response: recorded photon positions are spread out according to the point spread function (PSF)

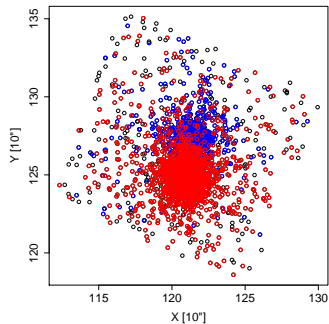


Source: XMM-Newton release notes

- PSFs overlap for sources near each other
- Aim: inference for number of sources and their intensities, positions and spectral distributions
- Key points of method:
  - (i) coherent Bayesian quantification of uncertainties
  - (ii) obtain posterior distribution of number of sources
  - (iii) use spectral information



Chandra observation of the Orion Nebula Cluster



Example photon assignment for XMM observation of FK and FL Aqr



# Spatial Data: Bayesian Data Generating Model

Observed quantities:

$N$  = total # photons (fix)

$(x_i, y_i)$  = spatial coordinates of photon  $i$

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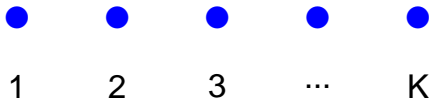
Observed quantities:

$N$  = total # photons (fix)

$(x_i, y_i)$  = spatial coordinates of photon  $i$

Model:

# sources:  $K \sim \text{Pois}(\kappa)$



# Spatial Data: Bayesian Data Generating Model

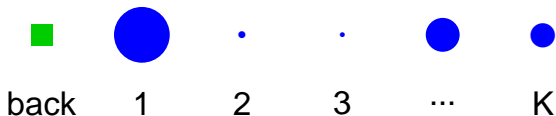
Observed quantities:

$N$  = total # photons (fix)

$(x_i, y_i)$  = spatial coordinates of photon  $i$

Model:

**True relative brightness:**  $(w_0, \dots, w_K) | K \sim \text{Dirichlet}(1, \dots, 1)$





# Spatial Data: Bayesian Data Generating Model

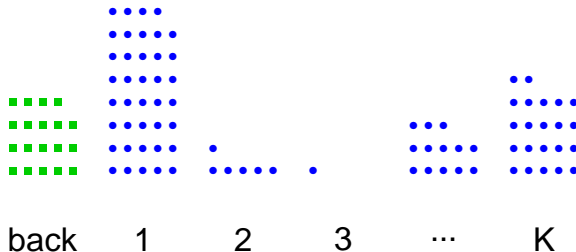
Observed quantities:

$N$  = total # photons (fix)

$(x_i, y_i)$  = spatial coordinates of photon  $i$

Model:

**Counts:**  $(n_0, \dots, n_K) | w, N \sim \text{Multinomial}(N; (w_0, \dots, w_K))$



# Spatial Data: Bayesian Data Generating Model

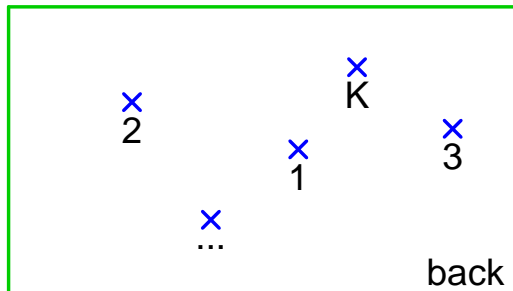
Observed quantities:

$N$  = total # photons (fix)

$(x_i, y_i)$  = spatial coordinates of photon  $i$

Model:

**Positions:**  $\mu_j | K \sim \text{Uniform over image, for } j = 1, 2, \dots, K$



# Spatial Data: Bayesian Data Generating Model

Observed quantities:

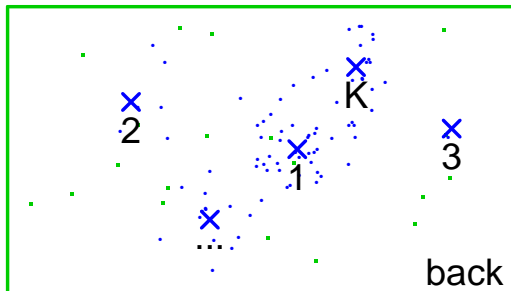
$N$  = total # photons (fix)

$(x_i, y_i)$  = spatial coordinates of photon  $i$

Model:

**Photon coords:**  $(x_i, y_i) | \text{source } j, \mu_j \sim \text{PSF}_j \text{ centred at } \mu_j$

**Background:**  $(x_i, y_i) | \text{background} \sim \text{Uniform over the image}$



# Spectral Data Model

Additionally observed:

$e_i$  = PI channel of photon  $i$

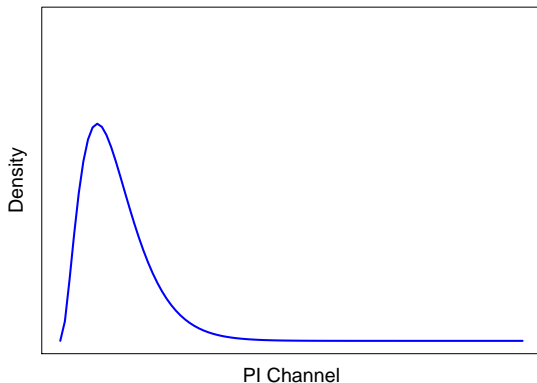
# Spectral Data Model

Additionally observed:

$e_i$  = PI channel of photon  $i$

Model:

**Photon energy:**  $e_i | \text{source } j, \alpha_j, \beta_j \sim \text{Gamma}(\alpha_j, \beta_j)$



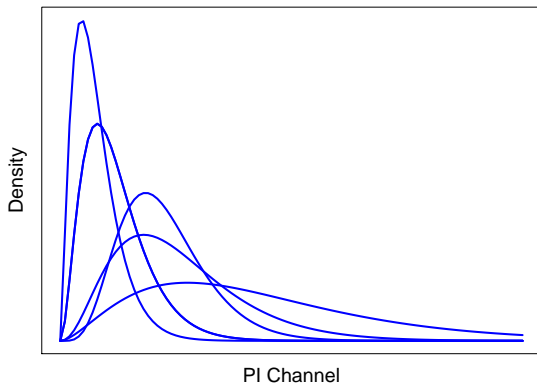
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# Spectral Data: Bayesian Data Generating Model

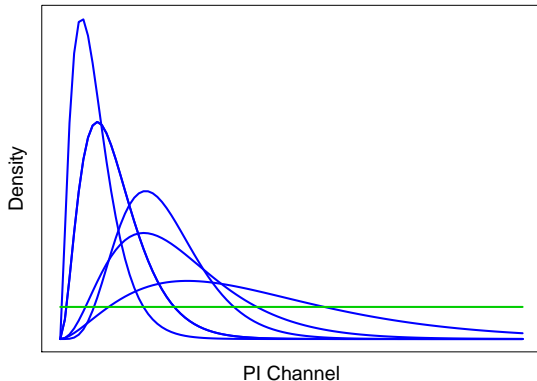
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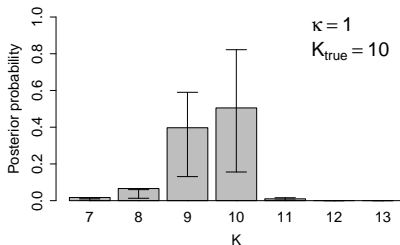
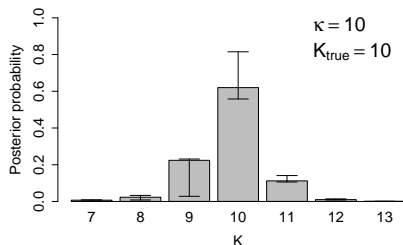
**Background:**  $e_i | \text{background} \sim \text{Uniform}(0, E_{\max})$



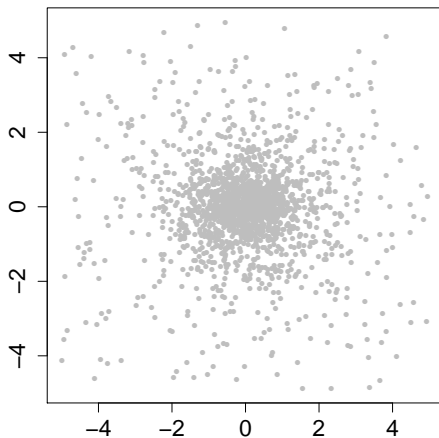
- **Final output:** joint posterior distribution of all the parameters
- **How we get there:** RJMCMC that combines algorithms of Richardson & Green 1997 and Wiper et al. 2001

Is this tractable?

- Knowledge of the PSF makes things much easier
- Inference is insensitive to the prior  $K \sim \text{Pois}(\kappa)$  e.g. for 20 simulated datasets each with 10 sources we have the following mean posterior distributions . . .

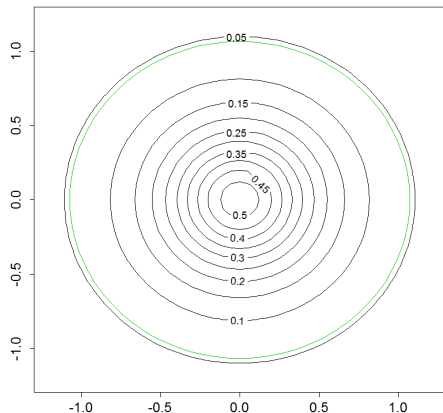
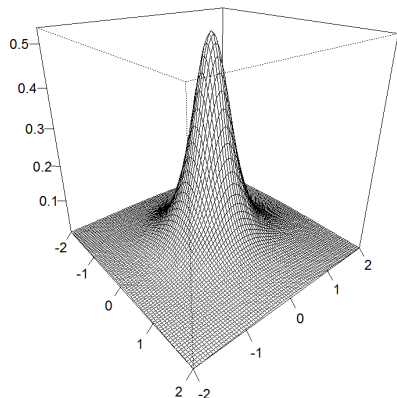






- 100 datasets simulated for each configuration
- Analysis with spatial-only model and full model

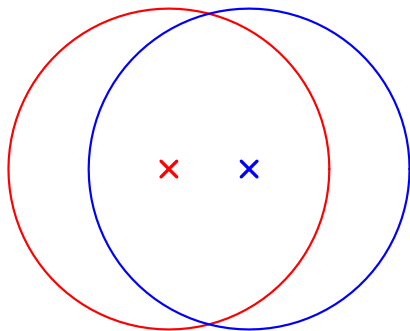
## Simulation Study: PSF (King 1962)



- King density has Cauchy tails
- Gaussian PSF leads to over-fitting in real data
- 'Source region': the region defined by PSF density greater than 10% of the maximum (essentially a circle with radius 1)

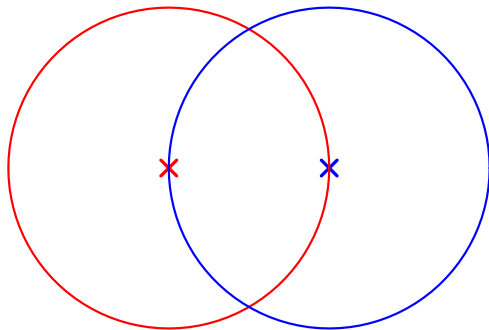
## Simulation Study: Spatial Data

Source separation:  $d = 0.5, 1, 1.5, 2$



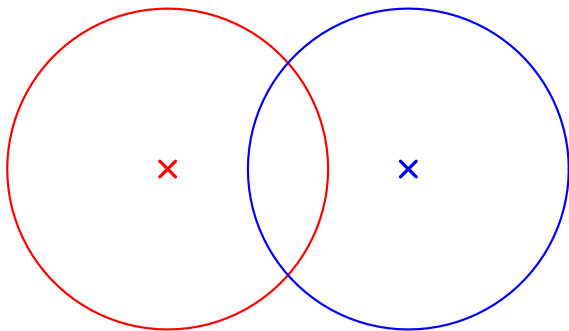
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Source separation:  $d = 0.5, 1, 1.5, 2$



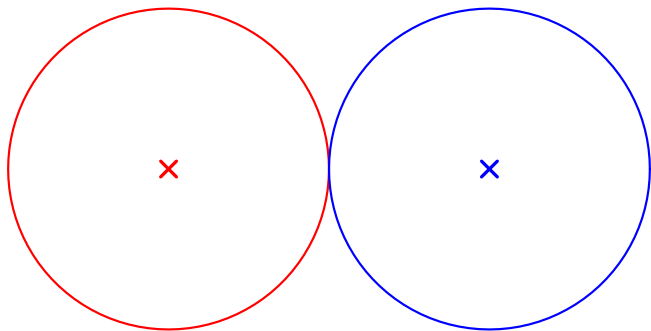
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Source separation:  $d = 0.5, 1, 1.5, 2$



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# Simulation Study: Spatial Data

Relative intensity:

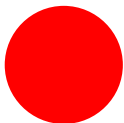
- Bright source:

$$n_1 \sim \text{Pois}(m_{\text{bright}} = 1000)$$

- Faint source:

$$n_2 \sim \text{Pois}(m_{\text{faint}} = 1000/r)$$

where  $r = 50, 10, 5, 2, 1$



$m_{\text{bright}} = 1000$



$m_{\text{faint}} = 20$

# Simulation Study: Spatial Data

Relative intensity:

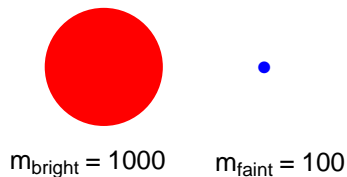
- Bright source:

$$n_1 \sim \text{Pois}(m_{\text{bright}} = 1000)$$

- Faint source:

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where  $r = 50, 10, 5, 2, 1$





# Simulation Study: Spatial Data

Relative intensity:

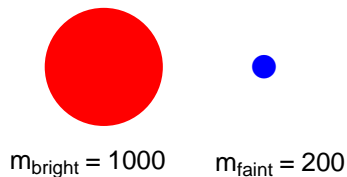
- Bright source:

$$n_1 \sim \text{Pois}(m_{\text{bright}} = 1000)$$

- Faint source:

$$n_2 \sim \text{Pois}(m_{\text{faint}} = 1000/r)$$

where  $r = 50, 10, 5, 2, 1$



# Simulation Study: Spatial Data

Relative intensity:

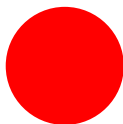
- Bright source:

$$n_1 \sim \text{Pois}(m_{\text{bright}} = 1000)$$

- Faint source:

$$n_2 \sim \text{Pois}(m_{\text{faint}} = 1000/r)$$

where  $r = 50, 10, 5, 2, 1$



$m_{\text{bright}} = 1000$



$m_{\text{faint}} = 500$

# Simulation Study: Spatial Data

Relative intensity:

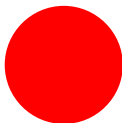
- Bright source:

$$n_1 \sim \text{Pois}(m_{\text{bright}} = 1000)$$

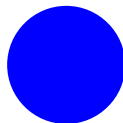
- Faint source:

$$n_2 \sim \text{Pois}(m_{\text{faint}} = 1000/r)$$

where  $r = 50, 10, 5, 2, 1$



$m_{\text{bright}} = 1000$

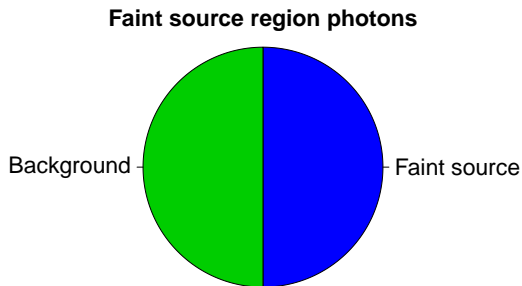


$m_{\text{faint}} = 1000$

Relative background:

$$n_0 \sim \text{Pois} \left( b \times \text{avg \# faint source photons in faint source region} \times \frac{\text{image area}}{\text{source region area}} \right)$$

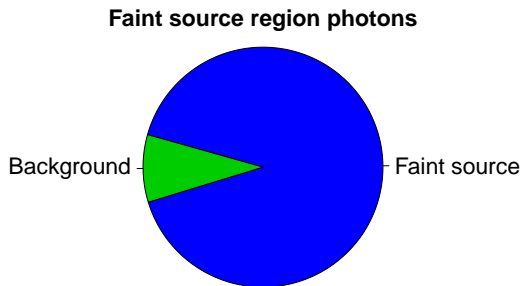
$b = 1, 0.1, 0.01, 0.001$



Relative background:

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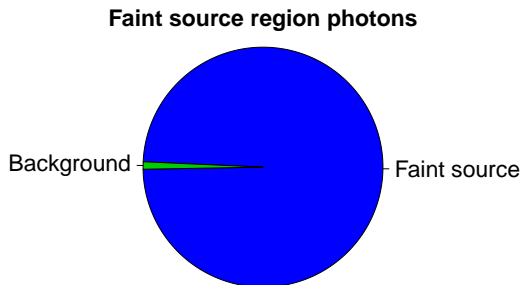
$b = 1, 0.1, 0.01, 0.001$



Relative background:

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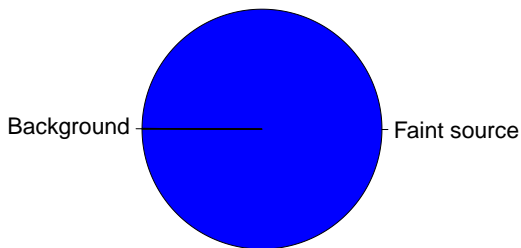


Relative background:

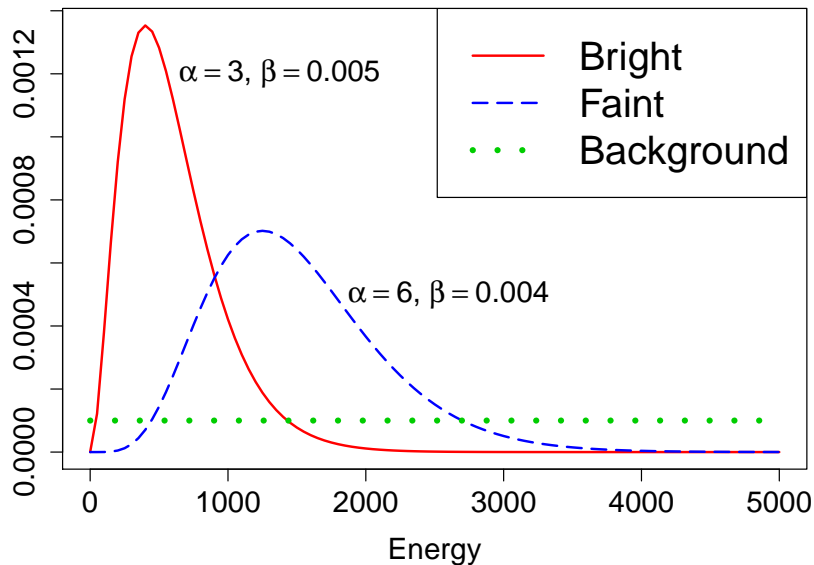
$$n_0 \sim \text{Pois} \left( b \times \text{avg \# faint source photons in faint source region} \times \frac{\text{image area}}{\text{source region area}} \right)$$

$b = 1, 0.1, 0.01, 0.001$

**Faint source region photons**



## Simulation Study: Spectral Data

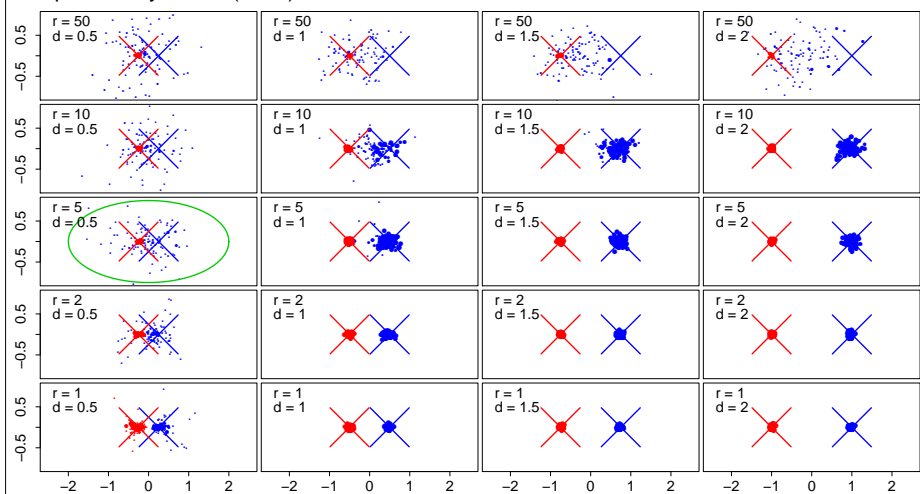




# Mean Posterior Positions (Strong Background, $b=1$ )

- Red = bright sources, blue = faint source
- $d$  = separation,  $r$  = relative intensity
- Size of dots  $\propto$  posterior probability of two sources

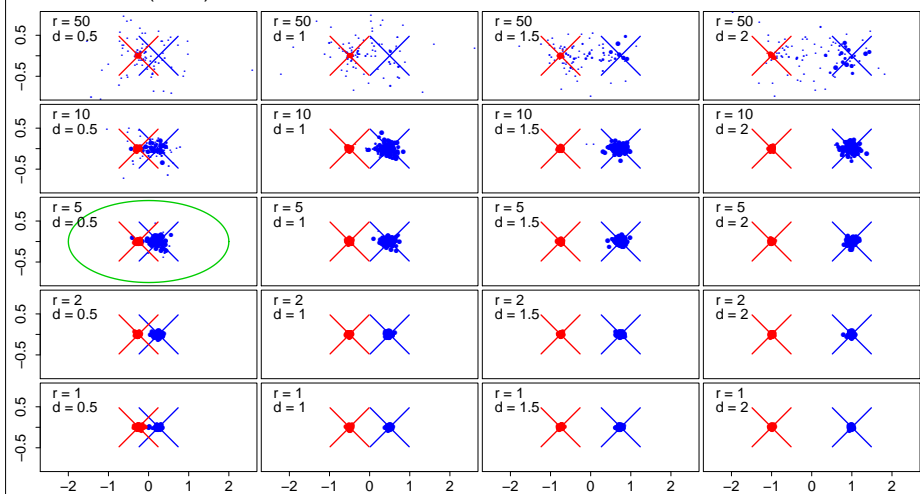
## Spatial-only model ( $b = 1$ )



# Mean Posterior Positions (Strong Background, $b=1$ )

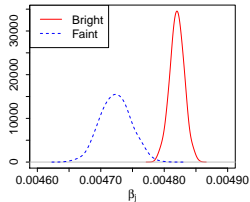
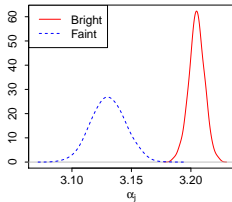
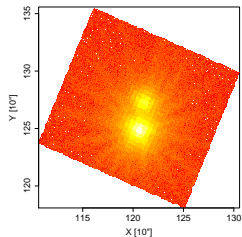
- Red = bright sources, blue = faint source
- $d$  = separation,  $r$  = relative intensity
- Size of dots  $\propto$  posterior probability of two sources

## Full model ( $b = 1$ )

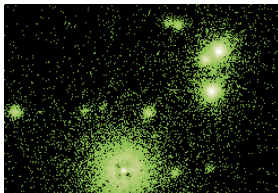


Paper gives two data analyses:

- **Briefly:** XMM data – binary source, FK and FL Aqr

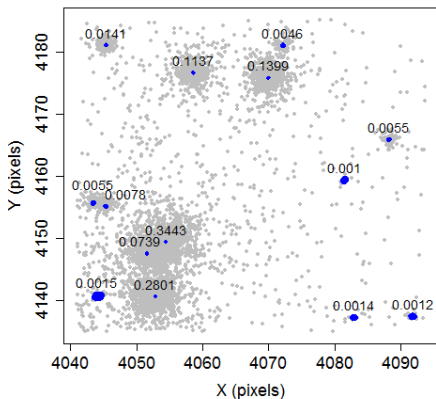


- **Focus:** Chandra image

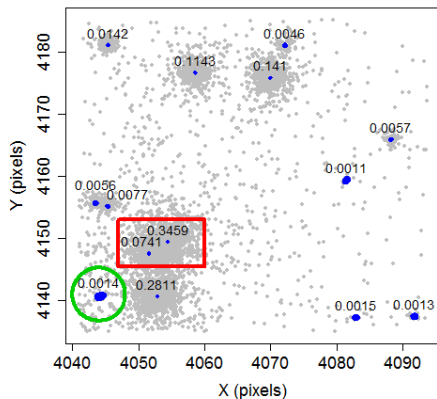


Chandra observation of the Orion Nebula Cluster

Spatial-only Model

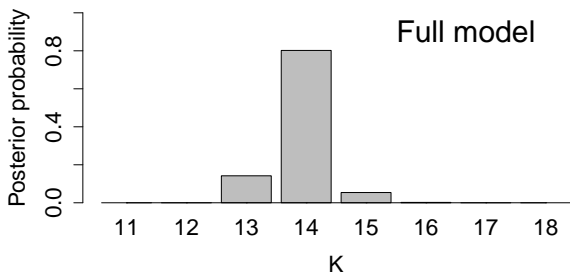
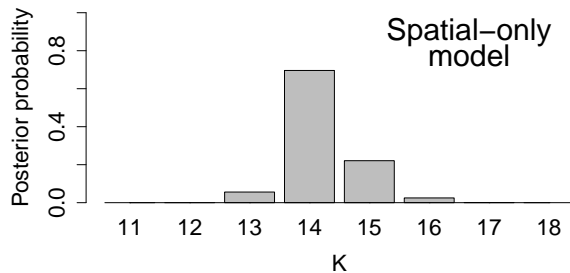


Full Model



- Part of Chandra observation of the Orion Nebula Cluster (distorted source cut out)
- Approximately  $25'' \times 25''$  in size

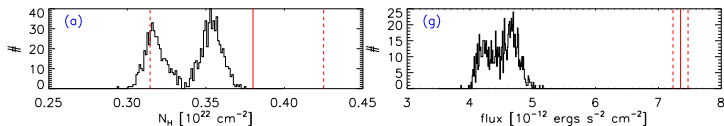
# Posterior distribution of $K$



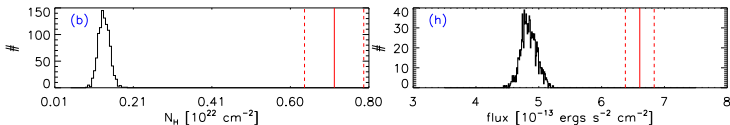
# Follow-up Spectral Analysis using CIAO/Sherpa v4.6

- Each iteration of our algorithm **probabilistically assigns every photon to a source or the background**
- Our assignments can be used to **repeatedly perform more detailed spectral analysis**
- The resulting histogram of spectral parameter fits enable us to quantify uncertainty

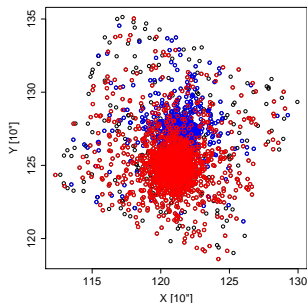
Bright source:



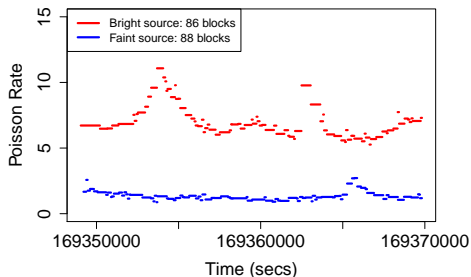
Faint source:



- **Concept:** for variable sources, modeling temporal data should further help separation
- Need a simple but flexible lightcurve model
- One idea: Poisson process with piecewise constant rate . . . as in Bayesian Blocks (Scargle 1998, Scargle et al. 2013):



Example photon assignment for XMM observation of FK and FL Aqr

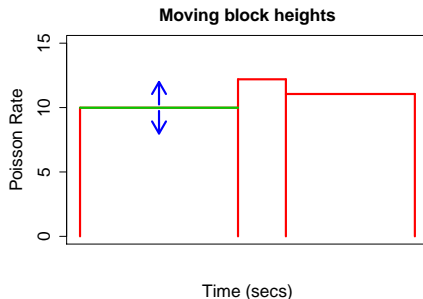


Bayesian blocks fits of the corresponding lightcurves

# How to implement the MCMC?

To allocate photons, we need to take account of our **uncertainties** about the underlying lightcurves. Computationally:

- MCMC iterations must update lightcurve models
- How to propose “nearby” models? Starting approach:
  - 1 Run Bayesian blocks on all data and then fix the breakpoints
  - 2 Set priors on the block heights and then update the heights in each MCMC iteration

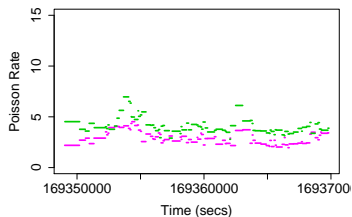
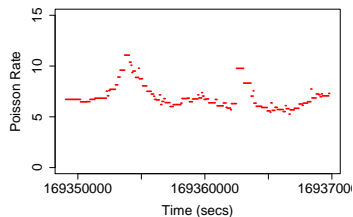


- More in the spirit of Bayesian blocks, we could also allow the breakpoints to move left or right



# How to implement the RJMCMC?

- RJMCMC will add further challenges
- When we “split” an existing source we will need to split its lightcurve model into two (stochastically)



## Scalability:

- Divide up image into sub-images e.g. Safarzadeh et al. (2014)
- Sample sub-images multiple times and combine posterior estimates . . . or the posterior distributions themselves e.g. Minsker et al. (2014)

## Additional improvements / directions:

- Instrument effects e.g. varying PSF
- Separation of extended sources and point sources
- Binning and LSST data

Thanks!