

### Interpretation of constrained climate model ensembles Ben Sanderson



## Outline

- A constrained ensemble indistinguishable, truth plus error or both?
- CMIP mean result: why is it so good?
- Improving confidence in multi-model projections
- A weighting scheme accounting for intermodel similarities

truth + error





Ensemble Interpretation

## indistinguishable

<ul> <li>Giorgi 2008</li> <li>Murphy et al. 2007</li> <li>Ruosteenoja et al. 2007</li> </ul>	<ul> <li>Moise and Hudson 2008</li> <li>Palmer et al. 2008</li> <li>Min et al. 2007</li> <li>Giorgi and Mearns 2002</li> <li>Pierce et al. 2009</li> <li>Perkins and Pitman 2009</li> </ul>	
<ul> <li>Raisanen and Ruokolainen</li> <li>Dettinger 2006</li> <li>Raisanen and Palmer 2001</li> </ul>	<ul> <li>Laurent and Cai 2007</li> <li>Shukla et al. 2006</li> <li>Dessai et al. 2005</li> <li>Watterson 2008</li> <li>Brekke et al. 2008</li> </ul>	•
	<ul> <li>Buser et al. 2009</li> <li>Smith et al. 2009</li> <li>Furrer et al. 2007</li> <li>Boulanger et al. 2007</li> <li>Greene et al. 2006</li> </ul>	•

## truth + error

unweighted

### cr. Claudia Tebaldi

## indistinguishable

<ul> <li>model distribution</li> <li>space-filling?</li> </ul>	<ul> <li>unknown distribution</li> <li>weighted by obs</li> <li>possibly 0/1 weight</li> </ul>
	unobserved truth
	•constrained by obs
	<ul> <li>decreasing uncertainty</li> </ul>

## truth + error

### Performance Metrics

Gleckler, P., *et al*, J. Geophys. Res (2008)



### Error of the mean

Knutti et al (2009)



$$\frac{1}{n} \sum ||m_i - O||^2 = \frac{1}{n} \sum ||m_i - M||^2 + ||O - M||^2$$

$$\frac{1}{n} \sum \|m_i - O\|^2 > \|O - M\|^2$$

Indistinguishable Mean Annan et al. (2010)

![](_page_8_Figure_0.jpeg)

### The mean result Reichler and Kim (2008)

![](_page_9_Figure_0.jpeg)

![](_page_10_Figure_0.jpeg)

Indistinguishable Mean

Annan and Hargreaves (2010)

![](_page_11_Figure_0.jpeg)

### Indistinguishable Mean

Annan and Hargreaves (2010)

![](_page_12_Figure_0.jpeg)

# CAMcube Optimal CPDN Optimal Mean Optimal Image: Comparison of the system of the syst

![](_page_13_Figure_1.jpeg)

Recipe for a perfect T+E ensemble for the present:

- independent irreducible errors
- sufficiently large ensemble
- perfect calibration

Truth + error by design

Sanderson & Knutti (in prep)

![](_page_14_Figure_0.jpeg)

### Case 1: A predictable system

Knutti & Sanderson (submitted)

![](_page_15_Figure_0.jpeg)

![](_page_16_Figure_0.jpeg)

### Case II: unconstrained Knutti & Sanderson (submitted)

![](_page_17_Figure_0.jpeg)

### Observable Constraints

Knutti & Sanderson (submitted)

![](_page_18_Figure_0.jpeg)

A (less) predictable system Sanderson (in prep)

![](_page_19_Picture_0.jpeg)

### Case III: structurally wrong

Knutti & Sanderson (submitted)

![](_page_20_Figure_0.jpeg)

![](_page_21_Picture_0.jpeg)

### Case IV: impossible constraint K

Knutti & Sanderson (submitted)

![](_page_22_Figure_0.jpeg)

"Common structural error may be difficult to separate from inter-model differences"

Knutti and Sanderson (submitted)

Present Truth+Error by design (with careats)

-common systematic errors-imperfect tuning-small sample

-model interdependency-feedback constraints-missing processes

Future

Indistinguishable (with careats)

![](_page_24_Figure_0.jpeg)

![](_page_25_Picture_0.jpeg)

![](_page_25_Picture_1.jpeg)

![](_page_26_Figure_0.jpeg)

![](_page_27_Figure_0.jpeg)

![](_page_28_Figure_0.jpeg)

Weighting

Sanderson & Knutti (in prep.)

![](_page_29_Figure_1.jpeg)

![](_page_30_Picture_0.jpeg)

Multi-Model Mean

![](_page_30_Figure_2.jpeg)

![](_page_30_Figure_3.jpeg)

![](_page_31_Figure_0.jpeg)

### Pattern Projections

Sanderson (in preparation)

![](_page_32_Figure_0.jpeg)

![](_page_33_Figure_0.jpeg)

![](_page_33_Figure_1.jpeg)

Annual Precipitation Change (cm) -40 -30 -20 -10 0 10 20 30 40

### Model Consistency

Sanderson (in preparation)

![](_page_34_Figure_0.jpeg)

### Representative estimate

Sanderson (in preparation)

## Conclusions

- Constrained ensembles like CMIP may be best understood as imperfect truth+error by design for observed climate periods
- Spread in the present day ensemble is likely due to a combination of systematic errors, tuning limitations and limited degrees of freedom, unlike future predictions which spread due to differences in feedbacks and forced response
- Some aspects of the climate system may be predictable, and will retain truth+error characteristics for a longer lead time
- A complete model weighting should include both aspects of model skill and inter-model similarity